

# Stochastic Biomodelling

Andrzej Mizera ([andrzej.mizera@uni.lu](mailto:andrzej.mizera@uni.lu))

Faculty of Science, Technology and Communication

University of Luxembourg



# Course content

## 1. Introduction

- Stochasticity in biological processes
- Deterministic vs stochastic biomodelling

## 2. Prerequisite:

- Crash course on probability theory

## 3. Stochastic modelling of chemical kinetics: the chemical master equation (CME)

## 4. Stochastic simulation of the CME – Gillespie's direct method algorithm

## 5. Practicals:

- Implementing the Gillespie's algorithm in MATLAB and investigating its characteristics on various biochemical systems
- Comparing the obtained simulation results with the solutions in the deterministic formulation

Some words on what is the role of mathematical modelling in Systems Biology

# Stochastic Biomodelling

---

Prerequisite: Crash course on probability theory

# Sample space

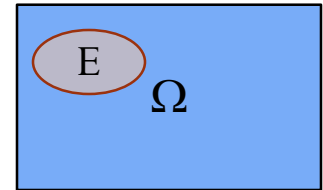
- **Experiments**: situations where the well defined outcomes occur randomly
- **Sample space**: the set of all possible outcomes of an experiment
- The sample space is denoted by  $\Omega$  and its element (a possible outcome) is  $\omega$ .
- **Exactly one outcome occurs in each experiment!**
- Examples:

	$\omega$	$\Omega$
Toss a coin	$\omega = \text{Head, Tail, (edge?)}$	$\Omega = \{H, T\}$
Roll a die	$\omega = 1, 2, 3, 4, 5, 6$	$\Omega = \{1, 2, 3, 4, 5, 6\}$
Sex of a newborn baby	$\omega = \text{Male, Female}$	$\Omega = \{M, F\}$

# Events

- A collection of possible outcomes of an experiment, or a subset of the sample space  $\Omega$ , is called an **event**  $E$ .

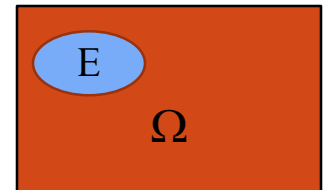
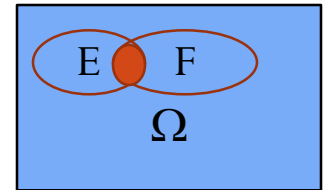
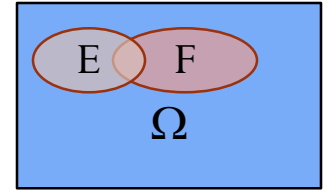
$$E \subseteq \Omega$$



- Events may be classified into four types:
  - **null event**, denoted  $\emptyset$ , is the empty subset of the sample space  $\Omega$
  - **atomic event** is a subset consisting of a single element of  $\Omega$ .
  - **compound event** is a subset consisting of more than one element of  $\Omega$ .
  - the **sample space**  $\Omega$  is also an event.

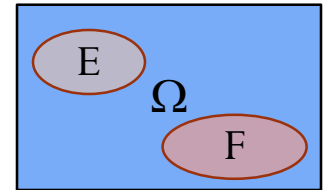
# Set operations on events

- The **union** of two events  $E$  and  $F$  (denoted  $E \cup F$ ) is an event that at least one of  $E$  and  $F$  occurs.
- The **intersection** of two events  $E$  and  $F$  (denoted  $E \cap F$ ) is an event that both  $E$  and  $F$  occur.
- The complement of an event  $E$  ( $E^c$  or  $\bar{E}$ ) is the event that  $E$  does not occur. It consists of all those elements of  $\Omega$  that are not in  $E$ .



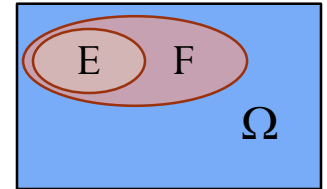
# Disjoint events

- Two events  $E$  and  $F$  are disjoint or mutually exclusive if they cannot both occur.
  - Their intersection is empty:  $E \cap F = \emptyset$
- Observe that:
  - $E \cap E^c = \emptyset$
  - $E \cup E^c = \Omega$



# True events

- The event  $E$  is **true** if the outcome of an experiment ( $\omega$ ) is contained in the event  $E$ , i.e. if  $\omega \in E$ .
- The event  $E$  **implies** the event  $F$  ( $E \Rightarrow F$ ) if the truth of  $F$  automatically follows from the truth of  $E$ .
  - If  $E$  is a subset of  $F$  then the occurrence of  $E$  necessarily implies occurrence of  $F$ :





# Probability axioms

- The real valued function  $P(\cdot)$  is a probability measure if it acts on subsets of  $\Omega$  and obeys the following axioms:
  - $P(\Omega) = 1$
  - If  $E \subseteq \Omega$ , then  $0 \leq P(E) \leq 1$
  - If  $E$  and  $F$  are disjoint, then  $P(E \cup F) = P(E) + P(F)$ 
    - If  $E_1, E_2, \dots, E_n$  are mutually disjoint, then  $P(\bigcup_{i=1}^n E_i) = \sum_{i=1}^n P(E_i)$

# Probability properties

- $P(\Omega) = 1$
- $P(E^c) = 1 - P(E)$
- $P(\emptyset) = 0$
- If  $E \subseteq F$ , then  $P(E) \leq P(F)$
- Addition law:  $P(E \cup F) = P(E) + P(F) - P(E \cap F)$ 
  - For disjoint  $E$  and  $F$ :  $P(E \cup F) = P(E) + P(F)$

# Conditional probability & independence

- The **conditional probability** (denoted by  $P(E|F)$ ) describes the probability of an event (E) given that another event (F) has already occurred:

$$P(E|F) = \frac{P(E \cap F)}{P(F)}, \text{ for } P(F) > 0$$

- Multiplication rule:  $P(E \cap F) = P(E) \cdot P(F|E)$
- Two events E and F are **independent** if and only if their joint probability equals the product of their probabilities:

$$P(E \cap F) = P(E) \cdot P(F)$$

- This implies:

$$P(E) = \frac{P(E) \cdot P(F)}{P(F)} = \frac{P(E \cap F)}{P(F)} = P(E|F)$$

# Independence

**Example:** A math teacher gave the class two tests. 25% of the class passed both tests and 42% of the class passed the first test. What percent of the students who passed the first test have also passed the second test?

Solution:

In other words, we need to find the probability that the second test was passed given that the first test was passed.

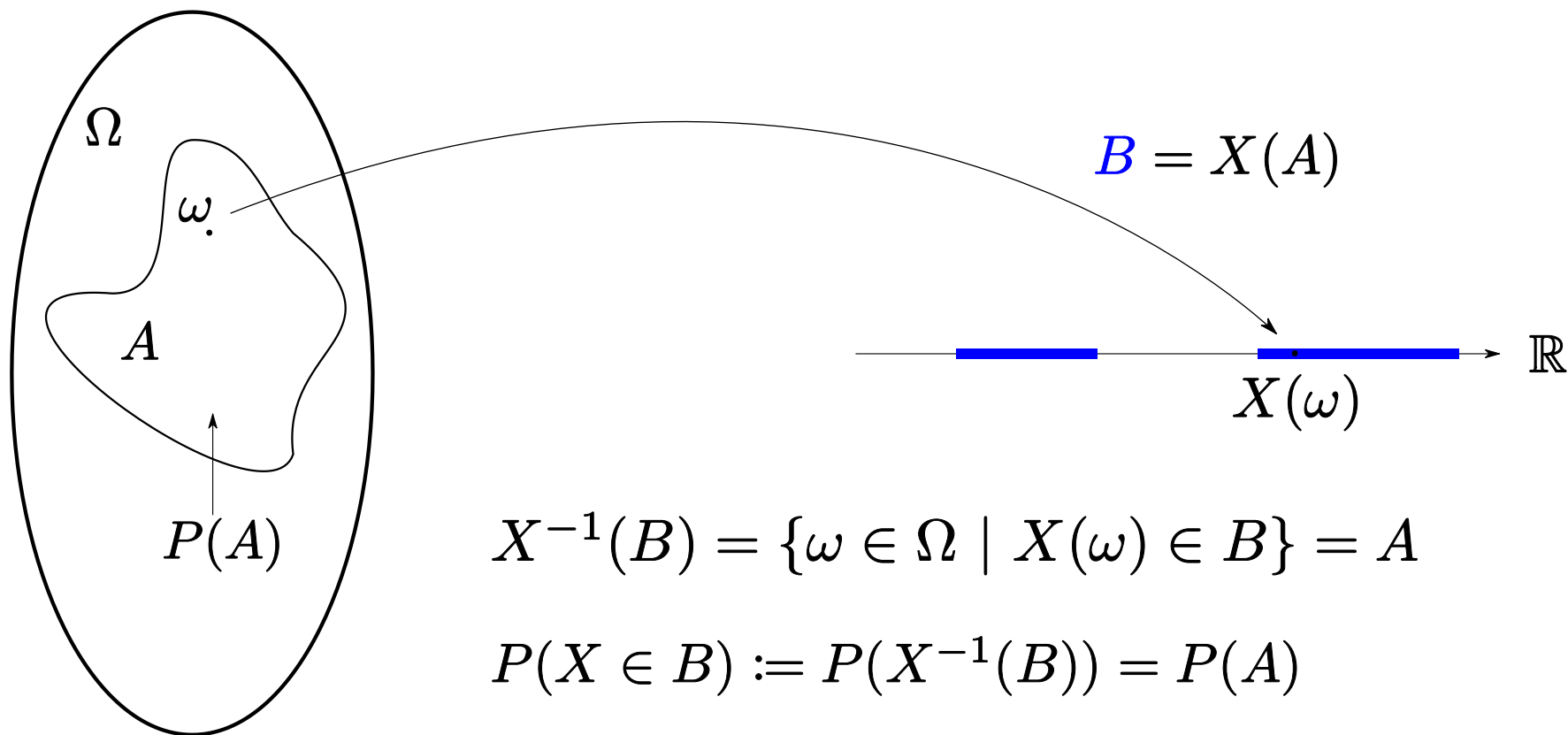
$$P(\text{Second} \mid \text{First}) = P(\text{First} \cap \text{Second}) / P(\text{First}) = 0.25/0.42 = 0.59$$

# Random variables

- The elements  $\omega$  of the sample space  $\Omega$  can be rather abstract objects.
- In practice, one often deals with simple numbers (integers, reals): one wants to ‘quantify’ the outcomes of random experiments and operate on them in mathematical terms (add, multiply, apply mathematical functions to them).
- The aim is thus to associate real numbers with the elements of the sample space. This idea gives rise to the concept of a **random variable**.
- For the purpose of this course a random variable  $X$  is defined to be a real-valued function (map)  $X : \Omega \rightarrow \mathbb{R}$  that assigns to each atomic event  $\omega \in \Omega$  a real number  $X(\omega)$ .

**Remark:** This is the ‘school’ definition of a random variable. In fact, it is not complete. The complete definition contains additionally a requirement of  $X$  to be a *measurable map*. The complete definition requires some basic knowledge of *measure theory*. Moreover, in general, the values of a random variable need not to be elements of  $\mathbb{R}$ , but can belong to some other set (e.g.,  $\mathbb{R}^n$ ).

# Random variables



# Random variables

- We distinguish between **discrete** and **continuous** random variables.
  - **Discrete random variable**: taking any of a specified finite or countable list of values
  - **Continuous random variable**: taking a value from a continuous range of values

# Discrete random variable

**Example:** Tossing a fair coin twice

- $\Omega = \{HH, HT, TH, TT\}$
- There may be **several** random variables associated with this experiment.
  - Let random variable  $X$  be the number of tails in the outcome:  
 $X(HH) = 0$ ;  $X(HT) = 1$ ;  $X(TH) = 1$ ;  $X(TT) = 2$ .

The **observed value** of a random variable is the number corresponding to the actual outcome, i.e., if the outcome of the experiment is  $\omega \in \Omega$ , then  $X(\omega) \in \mathbb{R}$  is the observed value.

- The observed value is denoted as  $x$ .
- Example: the set of possible observed values for  $X$  is  $S_X = \{X(\omega) \mid \omega \in \Omega\}$ , so in the example above it is:  $S_X = \{0, 1, 2\}$ .

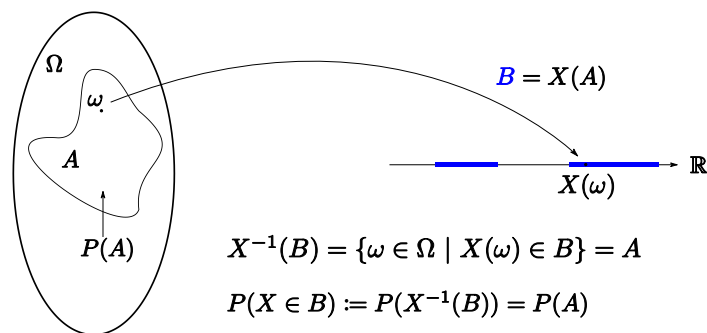
**Notice that the values in  $S_X$  need not to be equally likely!**



# Discrete probability distribution

- **Probability distribution** assigns a probability to each (measurable) subset of the possible outcomes of a random experiment.
- A discrete probability distribution is a probability distribution characterized by a **probability mass function (PMF)**, i.e., a function that gives the probability that a discrete random variable is exactly equal to some value.

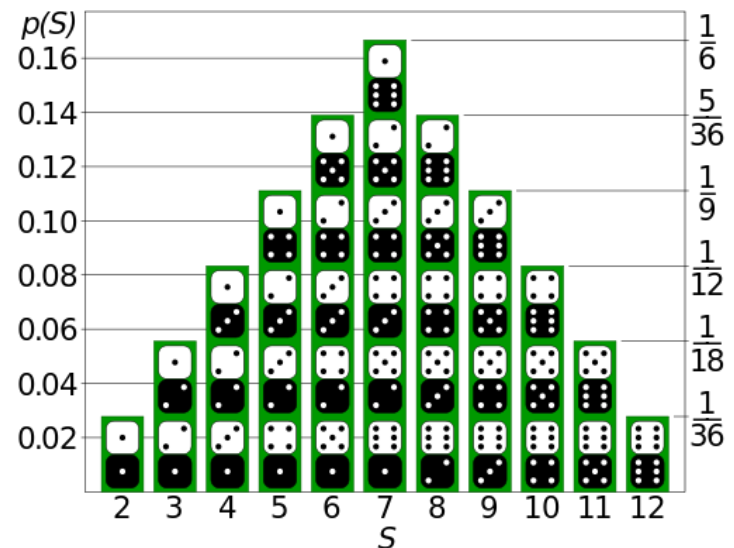
$$\Pr(X = x) = \sum_{\{\omega \in \Omega \mid X(\omega) = x\}} \Pr(\{\omega\})$$



# Probability mass function

**Example:** rolling two dice

- Let  $S$  be the sum of numbers on the two dice.
- $S_S = \{2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12\}$ .
- These values are not equally likely!



Source: Wikipedia

Value (s)	2	3	4	5	6	7	8	9	10	11	12
Pr(S = s)	1/36	2/36	3/36	4/36	5/36	6/36	5/36	4/36	3/36	2/36	1/36

The table provides a representation of the probability mass function for  $S$ .

# Cumulative distribution function

- **Cumulative distribution function (CDF)** is the probability that a real-valued random variable  $X$  will take a value less than or equal to  $x$ .

$$F_X(x) = \Pr(X \leq x) = \sum_{\{y \in S_X \mid y \leq x\}} \Pr(X = y)$$

- **Example:** sum of two dice

## PMF

<b>s</b>	2	3	4	5	6	7	8	9	10	11	12
<b>Pr(S = s)</b>	1/36	2/36	3/36	4/36	5/36	6/36	5/36	4/36	3/36	2/36	1/36

## CDF

<b>s</b>	2	3	4	5	6	7	8	9	10	11	12
<b>F<sub>S</sub>(s)</b>	1/36	3/36	6/36	10/36	15/36	21/36	26/36	30/36	33/36	35/36	36/36

# Expectation of a random variable

- The **expected value** (expectation, mean, average, first moment) of a random variable is the weighted average of all possible values that this random variable can take on, where the weights are the respective probabilities:

$$\mu = E(X) = \sum_{x \in S_X} x \cdot \Pr(X = x)$$

- Remarks:
  - The expected value is **not** a random variable!
  - It represents the value of the random variable, that is expected to get on average.

# Variance and standard deviation

- **Variance** (second central moment) measures how far a set of numbers are spread out.
- It is the **mean of the squared deviations** from the expected value  $E(X)$ :

$$\begin{aligned}\sigma^2 = \text{Var}(X) &= E[(X - E(X))^2] = \sum_{x \in S_X} \text{Pr}(X = x) \cdot (x - E(X))^2 \\ &= E(X^2) - (E(X))^2\end{aligned}$$

- **Standard deviation**: a measure of dispersion of a set of data values

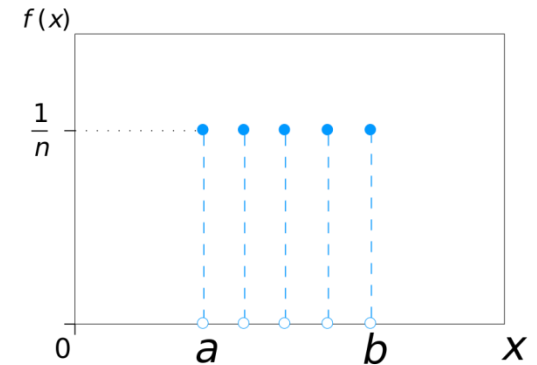
$$\sigma = SD(X) = \sqrt{\text{Var}(X)}$$

# Uniform distribution

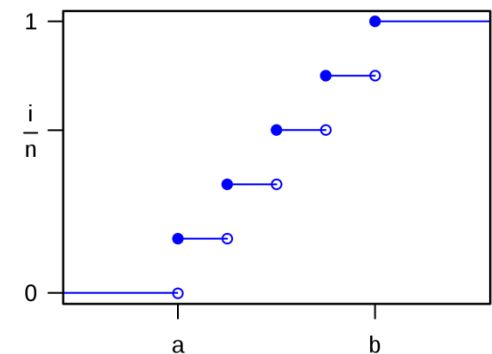
The **discrete uniform distribution** is a symmetric probability distribution whereby a finite number of values are equally likely to be observed; every one of  $n$  values has equal probability  $1/n$ .

- Sample space:  $S_X = \{1, 2, \dots, n\}$
- PMF:  $\Pr(X = k) = \begin{cases} \frac{1}{n} & k \in S_X \\ 0 & k \notin S_X \end{cases}$
- CDF:  $\Pr(X \leq k) = \frac{k}{n} \quad k \in S_X$
- Expectation:  $E(X) = \frac{n+1}{2}$
- Variance:  $Var(X) = \frac{n^2-1}{12}$

PMF



CDF



# Binomial distribution

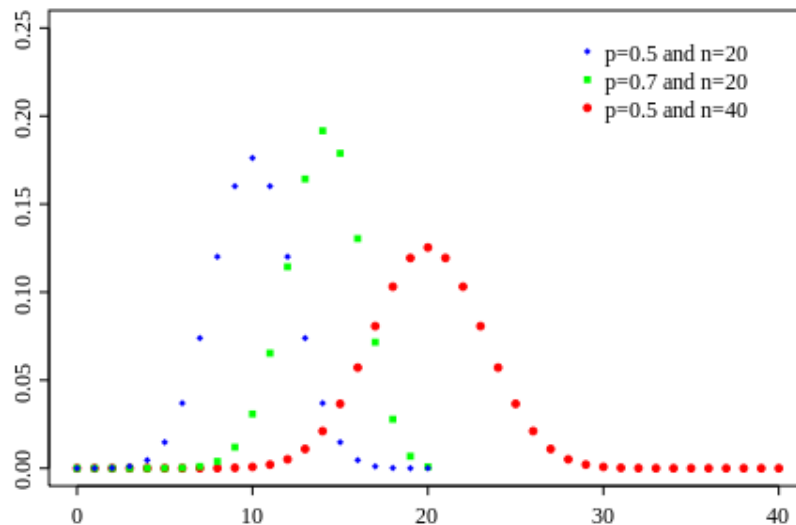
The **binomial distribution** with parameters  $n$  and  $p$  is the discrete probability distribution of the number of successes in a sequence of  $n$  independent experiments, each of which yields success with probability  $p$ .

- $X \sim B(n,p)$
- The experiment consists of  $n$  repeated trials.
- Each trial can result in **just two** possible outcomes: a success and a failure.
- The probability of success  $p$  is the same on every trial and the probability of failure is  $1-p$ .
- The trials are independent.

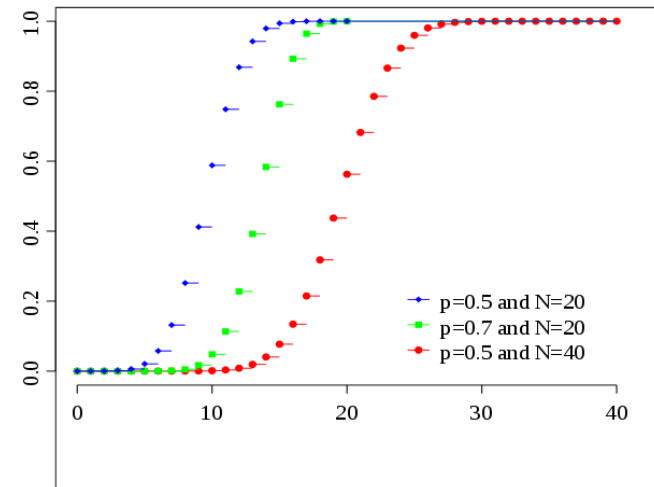
# Binomial distribution

- Sample space:  $S_X = \{0, 1, 2, \dots, n\}$
- PMF:  $\Pr(X = k) = \binom{n}{k} \cdot p^k \cdot (1 - p)^{n-k}$ ,  $k \in S_X$
- CDF:  $\Pr(X \leq k) = \sum_{i=0}^k \binom{n}{i} \cdot p^i \cdot (1 - p)^{n-i}$ ,  $k \in S_X$
- Expectation:  $E(X) = n \cdot p$
- Variance:  $Var(X) = n \cdot p \cdot (1 - p)$

PMF



CDF





# Continuous random variables

- **Continuous random variables** are appropriate if the result of an experiment is a **continuous** measurement, rather than a **count** of a discrete set.
  - **Example:** in the context of Systems Biology, such measurements often correspond to measurements of **time**.
- If  $X$  is a continuous random variable with sample space  $S_X$ , then for any particular  $x \in S_X$ , we generally have that  $\Pr(X = x) = 0$ .
  - **Intuition:** the sample space is so “large” and every possible outcome so “small” that the probability of any **particular** value is **vanishingly small**.
  - Therefore, the probability mass function introduced for discrete random variables is inappropriate for describing continuous random variables.

# Probability density function

- **Probability density function (PDF)**: If  $X$  is a continuous random variable, then there exists a function  $f_X(x)$ , called the probability density function, which satisfies the following:

1.  $f_X(x) \geq 0, \forall x;$

2.  $\int_{-\infty}^{\infty} f_X(x) dx = 1;$

3.  $\Pr(a \leq X \leq b) = \int_a^b f_X(x) dx$  for any  $a \leq b$ .

- Consequently:

$$\Pr(x \leq X \leq x + \delta x) = \int_x^{x+\delta x} f_X(y) dy \cong f_X(x) \delta x \quad (\text{for small } \delta x)$$

$$\Rightarrow f_X(x) \cong \frac{\Pr(x \leq X \leq x + \delta x)}{\delta x}$$

- If  $f_X: \mathbb{R} \rightarrow \mathbb{R}$ , then in the points where  $f_X$  is continuous we have that

$$f_X(x) = \lim_{\delta x \rightarrow 0} \frac{\Pr(x \leq X \leq x + \delta x)}{\delta x}.$$

# Probability density function

## Remarks:

- PDF values are **not** probabilities! The density can take values greater than 1.
- $\Pr(X \leq k) = \Pr(X < k)$  for continuous random variables.

# Cumulative distribution function

- **Cumulative distribution function (CDF)** for continuous random variables:

$$F_X(x) = \Pr(X \leq x) = \Pr(-\infty \leq X \leq x) = \int_{-\infty}^x f_X(y) dy.$$

- CDF values are probabilities!
- The distribution function is defined for all  $x \in \mathbb{R}$ , even if the sample space  $S_X$  is not the whole of the real line.
- $F_X(x) \in [0,1]$
- $F_X(-\infty) = 0$  and  $F_X(\infty) = 1$
- If  $a < b$ , then  $F_X(a) \leq F_X(b)$
- When  $X$  is continuous,  $F_X(x)$  is continuous. Also, by the *Fundamental Theorem of Calculus*, we have

$$\frac{d}{dx} F_X(x) = f_X(x).$$

# Expectation & variance

- The **expectation** of a continuous random variable  $X$  is given by

$$E(X) = \int_{-\infty}^{\infty} x \cdot f_X(x) dx$$

- The variance is given by

$$\text{Var}(X) = \int_{-\infty}^{\infty} [x - E(X)]^2 \cdot f_X(x) dx = \int_{-\infty}^{\infty} x^2 \cdot f_X(x) dx - [E(X)]^2 = E(X^2) - [E(X)]^2$$

# Uniform distribution

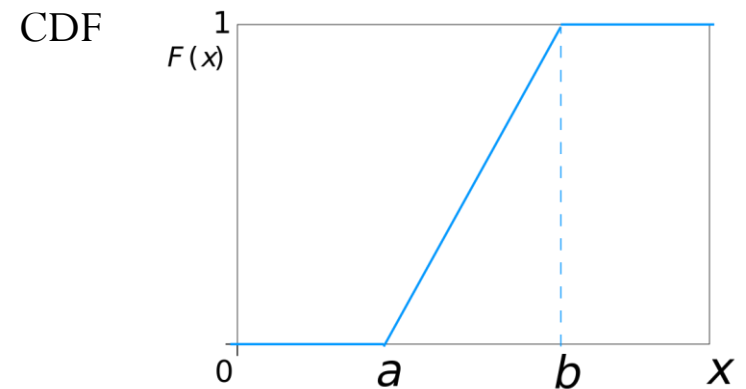
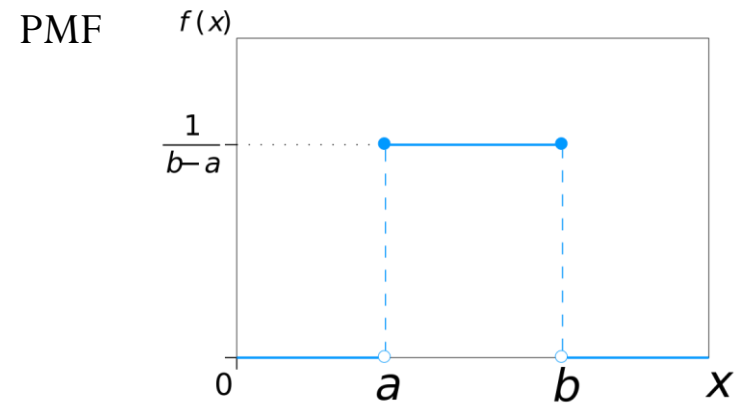
- **Uniform distribution**,  $X \sim U(a,b)$ , is a distribution that has a constant probability.

- PDF:  $f(x) = \begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$

- CDF:  $F(x) = \begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & x > b \end{cases}$

- Expectation:  $E(X) = \frac{a+b}{2}$

- Variance:  $Var(X) = \frac{(b-a)^2}{12}$



# Normal (Gaussian) distribution

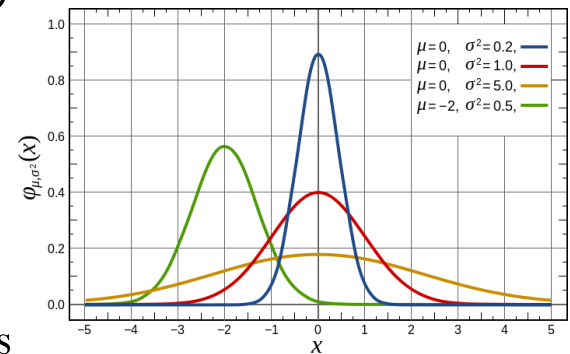
- A random variable  $X$  has a **normal distribution** with parameters  $\mu$  and  $\sigma^2$ , denoted  $X \sim N(\mu, \sigma^2)$  if it has pdf

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right\},$$

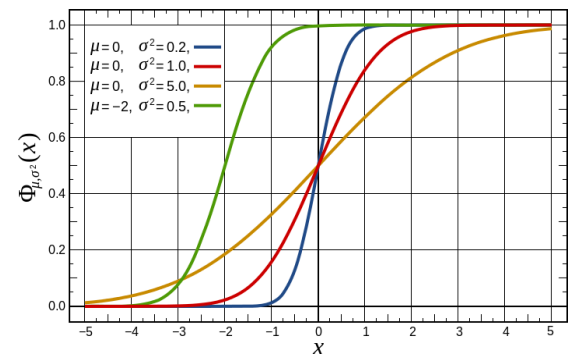
for  $\sigma > 0$ .

- It turns out that sums of random quantities often approximately follow a normal distribution.
  - Very important in statistics.
- CDF:  $\frac{1}{2}\left[1 + \operatorname{erf}\left(\frac{x-\mu}{\sigma\sqrt{2}}\right)\right]$
- Expectation:  $E(X) = \int_{-\infty}^{\infty} x \cdot f_X(x) dx = \mu$
- Variance:  $\operatorname{Var}(X) = \int_{-\infty}^{\infty} (x-\mu)^2 \cdot f_X(x) dx = \sigma^2$

PMF



CDF



# Exponential distribution

- The random variable  $X$  has an **exponential distribution** with parameter  $\lambda > 0$ , denoted  $X \sim \text{Exp}(\lambda)$ , if it has PDF

$$f_X(x) = \begin{cases} \lambda \cdot e^{-\lambda \cdot x} & x \geq 0, \\ 0 & \text{otherwise.} \end{cases}$$

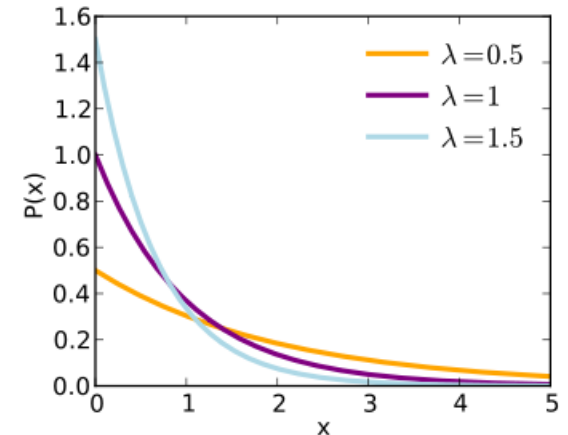
- The exponential distribution is the most important continuous distribution in the theory of discrete-event stochastic simulation.

- CDF:  $F_X(x) = \begin{cases} 0 & x < 0, \\ 1 - e^{-\lambda \cdot x} & x \geq 0. \end{cases}$

- Expectation:  $E(X) = \int_0^{\infty} x \cdot \lambda \cdot e^{-\lambda \cdot x} dx = \frac{1}{\lambda}$

- Variance:  $\text{Var}(X) = \frac{1}{\lambda^2}$

PMF



CDF

